
Geometry of Manifolds/Geometry in Physics
Exercise Sheet 9

Jonas Ziefle

10. Dezember 2019

Diese Aufgaben sind schriftlich auszuarbeiten und am 19. Dezember vor der Vorlesung abzugeben. Für jede Aufgabe gibt es 4 Punkte.

Zweierabgaben sind erlaubt. Bitte bei der ersten Abgabe Matrikelnummer(n) angeben.

Aufgabe 1. Show that a covariant derivative $\nabla: \Gamma(E) \rightarrow \Gamma(T^*M \otimes E)$ on a vector bundle $E \rightarrow M$ is a local operator and can therefore be restricted to open subsets.

Aufgabe 2. Show that every vector bundle $E \rightarrow M$ admits a covariant derivative (Hint: partition of unity). Show furthermore that the set of connections on $E \rightarrow M$ is an affine space with vector space

$$\Omega^1(M, \text{End}(E)) = \Gamma(T^*M \otimes \text{End}(E)),$$

where $\text{End}(E) = E^* \otimes E$.

Aufgabe 3. A connection ∇ on a real vector bundle E with a bundle metric $\langle \cdot \rangle$ is called *metric* if

$$d\langle \varphi, \psi \rangle = \langle \nabla \varphi, \psi \rangle + \langle \varphi, \nabla \psi \rangle$$

for all sections $\varphi, \psi \in \Gamma(E)$. Show that

- a) a connection is metric iff its connection forms with respect to orthonormal frames are skew symmetric,
- b) every vector bundle with bundle metric admits a metric connection, and
- c) the set of metric connections on $(E, \langle \cdot \rangle)$ is an affine space with underlying vector space equal to the space the 1-forms with values in skew symmetric endomorphisms of E .

Aufgabe 4. Denote by $E = U \times \mathbb{K}^r$ the trivial rank r vector bundle on a simply connected open subset $U \subset \mathbb{R}^n$. A connection on E is given by the connection form (with respect to the standard frame)

$$\omega = - \sum_{i=1}^n A_i dx_i$$

with $A_i \in C^\infty(U, \text{Mat}(r \times r, \mathbb{K}))$. Show that the existence of a parallel frame, i.e., a solution $\Phi \in \Gamma(U, GL_r(\mathbb{K}))$ to $\nabla \Phi = d\Phi + \omega \Phi = 0$, implies that

$$\frac{\partial}{\partial x_i} A_j - \frac{\partial}{\partial x_j} A_i = [A_i, A_j]$$

for all $i, j \in \{1, \dots, n\}$.