

Introduction to Commutative Algebra and algebraic Geometry Presence Exercise to Sheet 8

Exercise 1.

Compute $I \cap K[y, z]$ for $I = \langle x^2 + y^2 + 1, z - x - 1 \rangle$.

Can you generalise the result for $J = \langle f(x, y), z - x - 1 \rangle$ with $f \in K[x, y]$?

Solution: Choose $>_{lp}$ with $x > y > z$. By algorithm 2.5.3 we have to compute a Gröbner basis S of I w.r.t. $>_{lp}$.

$$\begin{aligned}
 f_1 &= x^2 + y^2 + 1 \\
 f_2 &= -x + z - 1 \\
 \text{spoly}(f_1, f_2) &= -(x^2 + y^2 + 1) - x(-x + z - 1) \\
 &= \\
 q_2 &= z \\
 r &= -y^2 - 1 - xz + x - z(-x + z - 1) \\
 &= x - y^2 - 1 - z^2 + z \\
 q_2 &= z - 1 \\
 r &= x - y^2 - 1 - z^2 + z - (-x + z - 1) \\
 &= -y^2 - z^2 + 2z - 2 \\
 \text{LM}(-y^2 - z^2 + 2z - 2) &= y^2 \\
 \text{LM}(f_1) &= x^2, \text{LM}(f_2) = x
 \end{aligned}$$

$\Rightarrow S = \{f_1, f_2, -y^2 - z^2 + 2z - 2\}$. By the product criterion this is a Gröbner basis of I .

$\Rightarrow I \cap K[y, z] = \langle -y^2 - z^2 + 2z - 2 \rangle$.

Can we generalise the result?

We observe that $I \cap K[y, z] = \langle -y^2 - z^2 + 2z - 2 \rangle = \langle f_1(z - 1, y) \rangle$.

Does this work for any $f \in K[x, y]$?

Take $J = \langle f(x, y), -x + z - 1 \rangle$. Write $\text{LM}(f) = x^k y^l$. w.l.o.g. we can assume $k > 0$, since otherwise J would already be given by a Gröbner basis by the product criterion. Further by our choice of monomial order this implies that $f \in K[y]$ and thus $J \cap K[y, z] = \langle f(y) \rangle$ which fits with our theory. We compute the spoly:

$$\begin{aligned}
 \text{spoly}(f(x, y), -x + z - 1) &= -f(x, y) - \text{LC}(f)x^{k-1}y^l(-x + z - 1) \\
 &= -\text{tail}(f) - \text{LC}(f)x^{k-1}y^l(z - 1)
 \end{aligned}$$

The leading Term of this is $\text{LC}(f)x^{k-1}y^l z$. If $k - 1 = 0$ the algorithm terminates and the output is $f(z - 1, y)$.

Otherwise we continue with indeterminate division with $-x + z - 1$:

$$\begin{aligned}
 q_2 &= \text{LC}(f)x^{k-2}y^l z \\
 r &= -\text{LC}(f)x^{k-1}y^l(z - 1) - \text{tail}(f) - \text{LC}(f)x^{k-2}y^l z(-x + z - 1) \\
 &= \text{LC}(f)x^{k-1}y^l - \text{tail}(f) - \text{LC}(f)x^{k-2}y^l z^2 + \text{LC}(f)x^{k-2}y^l z \\
 q_2 &= \text{LC}(f)x^{k-2}y^l z - \text{LC}(f)x^{k-2}y^l \\
 r &= \text{LC}(f)x^{k-1}y^l - \text{tail}(f) - \text{LC}(f)x^{k-2}y^l z^2 + \text{LC}(f)x^{k-2}y^l z + \text{LC}(f)x^{k-2}y^l(-x + z - 1) \\
 &= -\text{tail}(f) - \text{LC}(f)x^{k-2}y^l z^2 + \text{LC}(f)x^{k-2}y^l z + \text{LC}(f)x^{k-2}y^l(z - 1) \\
 &= -\text{tail}(f) - \text{LC}(f)x^{k-2}y^l z^2 + 2\text{LC}(f)x^{k-2}y^l z - \text{LC}(f)x^{k-2}y^l \\
 &= -\text{tail}(f) - \text{LC}(f)x^{k-2}y^l(z - 1)^2
 \end{aligned}$$

We see that continuous use of the the indeterminate division with $(-x + z - 1)$ will eliminate x and lead to the output $f(z - 1, y)$.
