

# Exercises: Mathematical Statistical Physics

Prof. Dr. P. Pickl  
Manuela Feistl

## Sheet 11

### Exercise 1: (Ergodicity)

Let  $(\Omega, \mathcal{A}, \mathbb{P})$  be a probability space and  $T : \Omega \rightarrow \Omega$  an ergodic measure-preserving transformation. Show that every map which is invariant under  $T$  is almost surely constant.

### Exercise 2: (Ergodicity)

- a) Let  $X = [0, 1)$  be the interval with endpoints identified,  $\lambda$  the 1-dimensional Lebesgue measure and  $R_\alpha : x \mapsto x + \alpha \pmod{1}$  be a rational rotation by  $\alpha = \frac{p}{q} \in \mathbb{Q}$ . Show that  $R_\alpha$  is not ergodic with respect to  $\lambda$  by showing that there exists an invariant function  $f : X \rightarrow \mathbb{R}$  for  $R_\alpha$  which is not constant  $\lambda$ -almost everywhere.

Hint: Try to use some trigonometric function.

- b) Let  $\underline{\alpha} = (\alpha_1, \alpha_2) \in \mathbb{R}^2$  and  $R_{\underline{\alpha}} : \mathbb{R}^2/\mathbb{Z}^2 \rightarrow \mathbb{R}^2/\mathbb{Z}^2$  be the translation on the torus given by  $R_{\underline{\alpha}}(x_1, x_2) = (x_1 + \alpha_1 \pmod{1}, x_2 + \alpha_2 \pmod{1})$ . Show that if there exists  $\underline{n} = (n_1, n_2) \in \mathbb{Z}^2$  such that  $\underline{n} \neq (0, 0)$  and  $\langle \underline{n}, \underline{\alpha} \rangle \in \mathbb{Z}$ , then  $R_{\underline{\alpha}}$  is not ergodic.

Hint: Look for a non-constant invariant trigonometric function  $f : \mathbb{R}^2/\mathbb{Z}^2 \rightarrow \mathbb{C}$ . You can then use it to find a real-valued non-constant invariant function.

### Exercise 3: (Probability measure)

Let  $(\Omega, \mathcal{A}, \mathbb{P})$  be a measurable space and  $T : \Omega \rightarrow \Omega$  a transformation. Show the following:

- a) If  $\mathbb{P}_1, \mathbb{P}_2$  are probability measures on  $(\Omega, \mathcal{A})$ , then any linear combination  $\lambda\mathbb{P}_1 + (1 - \lambda)\mathbb{P}_2$  is also a probability measure  $\forall \lambda \in [0, 1]$ .

Let  $(\Omega, \mathcal{A}, \mathbb{P})$  be a probability measure preserved by  $T$  and  $A \in \mathcal{A}$  with  $\mathbb{P}(A) > 0$ .

- b)  $\mathbb{P}_1(B) := \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(A)}$  and  $\mathbb{P}_2(B) := \frac{\mathbb{P}(A^c \cap B)}{\mathbb{P}(A^c)}$  are defining two measures. Are they also a probability measure?
- c) If  $A$  is invariant under  $T$  (i.e.  $T^{-1}(A) = A$ ), then  $\mathbb{P}_1, \mathbb{P}_2$  are invariant (i.e. measure-preserving) under  $T$ .

**Exercise 4:** (Vlasov equation)

Consider the following particle system

$$\begin{aligned}\dot{x}_i &= v_i \\ \dot{v}_i &= F(x_i) + \frac{1}{N} \sum_{j \neq i} G(x_i - x_j)\end{aligned}$$

Show that the empirical density

$$f(x, v, t) = \frac{1}{N} \sum_i \delta(x - x_i) \delta(v - v_i)$$

is a weak solution of the Vlasov equation

$$\partial_t f + v \cdot \nabla_x f + F(x) \cdot \nabla_v f + (G * \tilde{f}) \cdot \nabla_v f = 0,$$

where  $\tilde{f}(x, t) = \int f dv$  and  $G * \tilde{f} = \int G(x - y) \tilde{f}(y) dy$ . Consider therefore

$$\sum_{j \neq i} G(x_i - x_j) = \int G(x_i - y) \sum \delta(y - x_j) dx.$$