

Preparation course for the new Master Mathematical Physics Students 2018

8th October - 12th October, 2018

Fourth exercise sheet

1. Find the solution $x(\cdot)$ to the Newton's equations of
 - a) the motion in \mathbb{R}^3 for a point particle with mass $m > 0$ under the *gravitational force* $F_g := (0, 0, -mg)$ with $g > 0$, assuming that $x(t_0) = x_0 \in \mathbb{R}^3$ and $\dot{x}(t_0) = v_0 \in \mathbb{R}^3$, with $t_0 \in \mathbb{R}$;
 - b) the motion in \mathbb{R} for a point particle with mass $m > 0$ subject to the *Hooke's force* $F_H(x) := -kx$ with $k > 0$, assuming that $x(t_0) = x_0 \in \mathbb{R}$ and $\dot{x}(t_0) = v_0 \in \mathbb{R}$, with $t_0 \in \mathbb{R}$.
2. Write the Lagrangians for the two systems in the previous exercise.
3. Let D be an open set of \mathbb{R}^{3N} , $N \geq 1$. Consider the Lagrangian $\mathcal{L}: D \times \mathbb{R}^{3N} \rightarrow \mathbb{R}$ defined as

$$\mathcal{L}(q, \xi) := \sum_{k=1}^N \frac{1}{2} m_k |\xi_k|^2 - U(q),$$

where $m_k > 0$ for all $k \in \{1, \dots, N\}$ and $U \in C^n(D, \mathbb{R})$, $n \geq 2$. Given a *coordinate transformation in the configuration space* $\psi: \Lambda \times \mathbb{R} \rightarrow D$ such that $q = \psi(Q, t)$, compute the Lagrangian $\tilde{\mathcal{L}}: \Lambda \times \mathbb{R}^{3N} \rightarrow \mathbb{R}$ in the new coordinates.

4. Consider the Lagrangian

$$\mathcal{L}(q, \xi) = \frac{1}{2} m |\xi|^2 - U(q), \quad (q, \xi) \in \mathbb{R}^2 \times \mathbb{R}^2,$$

where $U(q) = U(|q|)$ (U is called a *central potential*).

- a) Which is a "suitable" coordinate transformation to rewrite the Lagrangian \mathcal{L} ? Once you have found it, write \mathcal{L} in the new coordinates.
 - b) Using the invariance of the Euler–Lagrangian equations under *coordinate transformations in the configuration space*, study the motion in the plane taking advantage of a *cyclic variable*.
5. Let D be an open set of \mathbb{R}^n . Let $\mathcal{L} \in C^k(D \times \mathbb{R}^n \times \mathbb{R}, \mathbb{R})$ with $k \geq 2$ be a Lagrangian. We define the *generalized energy* as

$$\mathcal{H}(q, \xi, t) := \left\langle \xi, \frac{\partial \mathcal{L}}{\partial \xi} \right\rangle_{\mathbb{R}^n} - \mathcal{L}(q, \xi, t).$$

Prove the following statement:

If $\phi: [t_1, t_2] \subset \mathbb{R} \rightarrow D$ is a solution of the Euler–Lagrange equations, then

$$\frac{d}{dt} \mathcal{H}(\phi(t), \dot{\phi}(t), t) = - \frac{\partial \mathcal{L}}{\partial t}(\phi(t), \dot{\phi}(t), t) \quad \forall t \in [t_1, t_2].$$