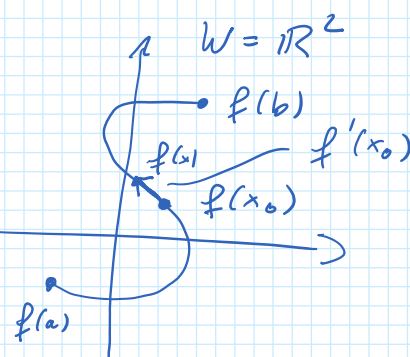
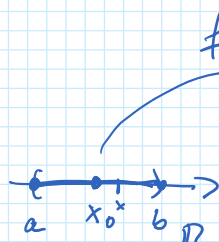
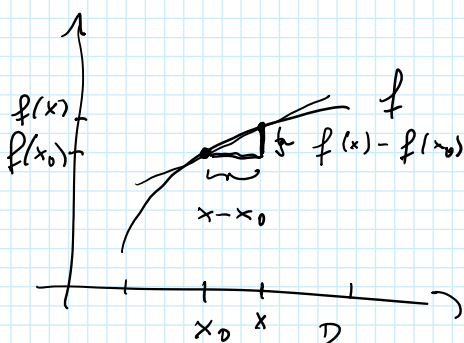


Recall that for $f: \mathbb{R} \supset D \rightarrow \mathbb{R}^2 (W, \|\cdot\|)$

$$\underline{f'(x_0)} := \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

$\forall (x_n) \text{ in } D \setminus \{x_0\} \text{ with } \lim_{n \rightarrow \infty} x_n = x_0$
 $\lim_{n \rightarrow \infty} \frac{f(x_n) - f(x_0)}{x_n - x_0}$ exists.

$$= \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$



$f'(x_0)$ = slope of tangent
to the graph at $(x_0, f(x_0))$

$f'(x_0) \in W$
= velocity vector

Def.: Let $n \in \mathbb{N}$, $D \subset \mathbb{R}^n$ open, $(W, \|\cdot\|)$ a normed space. For $x \in D$ and $j \in \{1, \dots, n\}$ a function $f: D \rightarrow W$ is called partially differentiable in the j th coord. direction at x , iff the limit

$$\lim_{h \rightarrow 0} \frac{f(x + h e_j) - f(x)}{h} = \lim_{h \rightarrow 0} \frac{f(x_1, x_2, \dots, x_j + h, \dots, x_n) - f(x_1, \dots, x_n)}{h}$$

exists. One writes

$$\frac{\partial f}{\partial x_j}(x) = \partial_j f(x) := \lim_{h \rightarrow 0} \frac{f(x + h e_j) - f(x)}{h}$$

and calls the vector $\partial_j f(x) \in W$ the j th partial

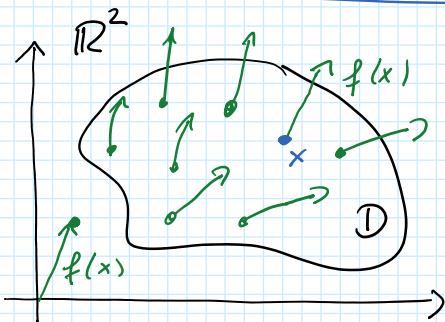
and calls the vector $\partial_j f(x) \in W$ the j th partial derivative at x .

If f is partially diff. and the partial derivatives $\partial_j f: D \rightarrow W$ are cont. fcts., then f is called cont. part. diff. The vector space of c.p.d. fcts on $D \subset \mathbb{R}^n$ is denoted by $C^1(D, W)$.

The gradient of f at x is

$$\nabla f(x) := (\partial_1 f(x), \dots, \partial_n f(x)) \in W^n$$

Def.: A map $f: \mathbb{R}^n \supset D \rightarrow \mathbb{R}^n$ is called a vector field.



Ex.: The gradient

$\nabla f: D \rightarrow \mathbb{R}^n$
of a fct. $f: D \rightarrow \mathbb{R}$

defines a vector field.

Def.: A fct. $f: \mathbb{R}^n \supset D \rightarrow W^{\leftarrow (k-\text{VSp.})}$ is called r -times cont. part. diff., iff for all $j = (j_1, \dots, j_r)$, $j_i \in \{1, \dots, n\}$

- f is c.p.d.
- $\partial_{j_1} f$ is c.p.d.
- $\partial_{j_2} \partial_{j_1} f$ is c.p.d.
- \vdots

- $\partial_{j_1} f$ is c.p.d.
- $\partial_{j_2} \partial_{j_1} f$ is c.p.d.
- \vdots
- $\partial_{j_r} \dots \partial_{j_1} f$ is continuous

The \mathbb{K} -vector space of r -times c.p.d. fcts is denoted by $C^r(D, W)$.

Def.: Let $D \subset \mathbb{R}^n$, $g \in C^1(D, \mathbb{R}^n)$, $f \in C^2(D, \mathbb{R})$.

Then $\operatorname{div} g: D \rightarrow \mathbb{R}$, $x \mapsto \operatorname{div} g(x) := \sum_{j=1}^n \frac{\partial g_j}{\partial x_j}(x)$

is called the divergence of g ,

$$\operatorname{curl} g: D \rightarrow \mathbb{R}^3, x \mapsto \operatorname{curl} g(x) := \begin{pmatrix} \partial_2 g_3(x) - \partial_3 g_2(x) \\ \partial_3 g_1(x) - \partial_1 g_3(x) \\ \partial_1 g_2(x) - \partial_2 g_1(x) \end{pmatrix}$$

for $n=3$ is called the curl of g ,

and

$$\Delta f: D \rightarrow \mathbb{R}, x \mapsto \Delta f(x) := \left(\operatorname{div}(\nabla f) \right)(x) \\ = \sum_{j=1}^n \frac{\partial^2 f}{\partial x_j^2}(x)$$

is called Laplace of f .

Ex. 1: Let $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$, $x \mapsto g(x) = x$ ($g = \operatorname{id}$)

and $f: \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}$, $x \mapsto \|x\|_2$.

Compute $\operatorname{div}(g)$ and Δf .

Thm. (Schwarz)

Let $f \in C^2(D, W)$, $D \subset \mathbb{R}^n$.

Then $\forall x \in D$, $j, i \in \{1, \dots, n\}$

$$\partial_j \partial_i f(x) = \partial_i \partial_j f(x)$$

Corollary: Let $D \subset \mathbb{R}^3$, $f \in C^2(D, \mathbb{R})$ and $g \in C^2(D, \mathbb{R}^3)$.

Then $\operatorname{curl}(\nabla f) = 0$ and $\operatorname{div}(\operatorname{curl} g) = 0$

Def.: Let V be a real normed space, W a normed space,

$D \subset V$ open and $f: D \rightarrow W$.

The directional derivative of f at $x \in D$ in the direction $v \in V$ is

$$\partial_v f(x) := \lim_{h \rightarrow 0} \frac{f(x + hv) - f(x)}{h} = \frac{d}{dh} f(x + hv) \Big|_{h=0}$$

if the limit exists.

Example: For $f: \mathbb{R}^n \rightarrow W$ we have $\partial_{e_j} f(x) = \partial_j f(x)$.

Different viewpoint: Derivative as lin. approx.

For $f: \mathbb{R} \rightarrow W$ differentiability at $x_0 \in \mathbb{R}$ means

$$\textcircled{0} = \lim_{x \rightarrow x_0} \left(\frac{f(x) - f(x_0)}{x - x_0} - f'(x_0) \right) =: \lim_{x \rightarrow x_0} \frac{\varphi(x, x_0)}{x - x_0}$$

where $\varphi(x, x_0) = f(x) - f(x_0) - f'(x_0)(x - x_0)$

or, after reshuffling

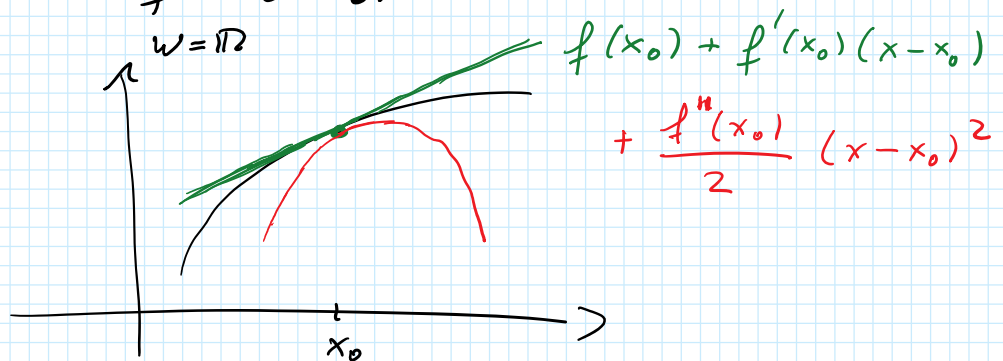
$$f(x) = \underbrace{f(x_0) + f'(x_0) \cdot (x - x_0)}_{(*)} + \varphi(x, x_0)$$

where

$$\varphi(x, x_0) = o(|x - x_0|) \Leftrightarrow \lim_{x \rightarrow x_0} \frac{|\varphi(x, x_0)|}{|x - x_0|} = 0$$

The map $\mathbb{R} \rightarrow W$, $x \mapsto f'(x_0) \cdot x$ is \mathbb{R} -linear
and the map $\mathbb{R} \rightarrow W$, $x \mapsto f(x_0) + f'(x_0)(x - x_0)$
is affine- \mathbb{R} -linear.

Hence, we think of $(*)$ as the (affine) linear
approximation to f near x_0 .



Def.: Total derivative

Let V be a finite dim. real vector space,
 W a normed space, $G \subset V$ open and $f: G \rightarrow W$.
 f is differentiable at $x_0 \in G$, iff there exist
an \mathbb{R} -linear map $A: V \rightarrow W$ such that

$$\lim_{x \rightarrow x_0} \frac{f(x) - f(x_0) - A(x - x_0)}{\|x - x_0\|_V} = 0 \quad \left(\begin{array}{l} \text{here } \|\cdot\|_V \text{ is any} \\ \text{norm on } V \end{array} \right)$$

Then A is uniquely determined (Ex. 2: prove this!),
is denoted by $Df|_{x_0}$, and called the total derivative
or the differential of f at x_0 .

If $f: G \rightarrow W$ is diff. at all $x \in G$, then f is called
differentiable on G and

$Df: G \rightarrow \mathcal{L}(V, W)$, $x \mapsto Df|_x$
is a fct. on G taking values in the linear maps
from V to W .

Rem.: $f: G \rightarrow W$ is diff. at x_0

$$\Rightarrow \boxed{f(x) = f(x_0) + \underbrace{Df|_{x_0}}_{\rightarrow 0} \underbrace{(x - x_0)}_{\rightarrow 0} + \underbrace{\sigma(\|x - x_0\|_V)}_{\text{faster } \rightarrow 0}}$$

Example: Let $L: V \rightarrow W$ be an \mathbb{R} -lin. map.

$$\begin{aligned} \text{Then } L(x) &= L(x_0 + x - x_0) = L(x_0) + L(x - x_0) \\ &=: L(x_0) + DL|_{x_0}(x - x_0) \end{aligned}$$

and hence $DL|_{x_0} = L$.

$$f(x) = x, \quad f'(x) = 1 \quad ?$$

Thm.: Let $G \subset \mathbb{R}^n$ and let $f: G \rightarrow \mathbb{K}^m$ be differentiable at $x_0 \in G$. Then

$$(Df|_{x_0})_{ij} = \frac{\partial f_i}{\partial x_j}(x_0)$$

or, more explicitly,

$$Df|_{x_0} = \begin{pmatrix} \partial_1 f_1(x_0) & \cdots & \partial_n f_1(x_0) \\ \vdots & & \vdots \\ \partial_1 f_m(x_0) & \cdots & \partial_n f_m(x_0) \end{pmatrix} \left. \vphantom{\begin{pmatrix} \partial_1 f_1(x_0) \\ \vdots \\ \partial_1 f_m(x_0) \end{pmatrix}} \right\} \begin{array}{l} m \text{ rows} \\ \\ n \text{ columns} \end{array}$$

$$= \begin{pmatrix} \nabla f_1(x_0) \\ \vdots \\ \nabla f_m(x_0) \end{pmatrix} \quad \text{"Jacobi matrix"}$$

Thm.: Let $G \subset \mathbb{R}^n$ open and $f \in C^1(G, \mathbb{K}^m)$.

Then f is differentiable.

\uparrow
cont. part. diff.

cont. part. diff. \Rightarrow differentiable \Rightarrow part. diff.

\Downarrow

continuous

None of the implications holds in the reversed direct. ∇

But

cont. part. diff \Leftrightarrow diff. with cont. derivative

Thm.: Chain rule

Let U, V be finite dim. real vector spaces,

W a normed space, $G \subset U$, $H \subset V$ open and

$g: G \rightarrow V$, $f: H \rightarrow W$ maps with $g(G) \subset H$, i.e.

$$U \supset G \xrightarrow{g} H \subset V \xrightarrow{f} W.$$

If g is diff. at $x \in G$ and f is diff. at $g(x) \in H$,

then $f \circ g: G \rightarrow W$ is diff. at x and

$$D(f \circ g)|_x = \underbrace{Df|_{g(x)}}_{W \leftarrow V} \cdot \underbrace{Dg|_x}_{V \leftarrow U}$$

Corollary: For $f \in C^1(G, W)$, $G \subset V$, $x_0 \in G$, and

$v \in V$ we have

$$\partial_v f(x_0) = Df|_{x_0} v$$

Ex. 3: prove this ∇

$G \subset V$

For $f: G \rightarrow W$ the differential Df is a map

$Df: G \rightarrow \mathcal{L}(V, W)$. Thus the "second derivative"

$D(Df)$ is a map

$$D(Df): G \rightarrow \mathcal{L}(V, \mathcal{L}(V, W)) \cong \mathcal{L}_2(V \times V, W)$$

and the k th derivation $:=$ bilinear maps
 $V \times V \rightarrow W$

$$D^k f: G \rightarrow \mathcal{L}_k(\underbrace{V \times \dots \times V}_{k\text{-copies}}, W).$$

Thm. Taylor

Let $G \subset V$ open, $x_0 \in G$, and $\delta > 0$ s.t. $B_\delta(x_0) \subset G$.

Then for any $f \in C^k(G, W)$ and $x \in B_\delta(x_0)$

$$f(x) = f(x_0) + Df|_{x_0} \underbrace{(x-x_0)}_{=: h} + \frac{1}{2} D^2 f|_{x_0}(h, h) + \dots \\ \dots + \frac{1}{k!} D^k f|_{x_0}(h, \dots, h) + o(\|h\|_V^k)$$

Def.: Let X be a ^{top. space} and $f: X \rightarrow \mathbb{R}$. A point $x_0 \in X$ is called a (strict) local maximum of f , iff $\exists U \subset \mathcal{U}(x_0)$ s.t.

$$\forall x \in U \setminus \{x_0\}: f(x) \leq f(x_0)$$

loc. minimum analogous.

Thm.: Let $G \subset V$ and $f \in C^1(G, \mathbb{R})$ have a local extremum at $x_0 \in G$. Then $Df|_{x_0} = 0$.

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Thm.: Let $G \subset V$ and $f \in C^2(G, \mathbb{R})$ and $x_0 \in G$ such that $Df|_{x_0} = 0$.

(a) If $D^2f|_{x_0}(h, h) > 0 \quad \forall h \in V \setminus \{0\}$, then

f has a strict local minimum at x_0

(b) $D^2f|_{x_0}(h, h) < 0 \quad \forall h \in V \setminus \{0\} \Rightarrow$ strict. loc. max. at x_0

(c) If $D^2f|_{x_0}$ is indefinite, then f has no local extremum at x_0