

FOUNDATIONS OF QUANTUM MECHANICS

In-class problems for the exercise class

Problem 5: Conserved quantities

Recall the equation of motion of Newtonian mechanics:

$$m_i \frac{d^2 \mathbf{Q}_i}{dt^2} = -\nabla_i V(\mathbf{Q}_1, \dots, \mathbf{Q}_N). \quad (1)$$

Suppose that V is invariant under rotations and translations:

$$V(R\mathbf{Q}_1 + \mathbf{a}, \dots, R\mathbf{Q}_N + \mathbf{a}) = V(\mathbf{Q}_1, \dots, \mathbf{Q}_N) \quad (2)$$

for all $\mathbf{a} \in \mathbb{R}^3$ and $R \in SO(3)$. Show that

$$\text{the energy } E = \sum_{k=1}^N \frac{m_k}{2} \mathbf{v}_k^2 + V(\mathbf{Q}_1, \dots, \mathbf{Q}_N) \quad (3)$$

$$\text{the momentum } \mathbf{p} = \sum_{k=1}^N m_k \mathbf{v}_k \quad (4)$$

$$\text{the angular momentum } \mathbf{L} = \sum_{k=1}^N m_k \mathbf{Q}_k \times \mathbf{v}_k \quad (5)$$

are conserved.

Problem 6: Galilean relativity

A Galilean change of space-time coordinates (“Galilean boost”) is given by

$$\mathbf{x}' = \mathbf{x} + \mathbf{v}t, \quad t' = t \quad (6)$$

with a constant $\mathbf{v} \in \mathbb{R}^3$ called the relative velocity.

(a) Show that if V is translation invariant then Newton’s equation of motion is invariant under Galilean boosts: If $t \mapsto (\mathbf{Q}_1, \dots, \mathbf{Q}_N)$ is a solution then so is $t \mapsto (\mathbf{Q}'_1, \dots, \mathbf{Q}'_N)$.

(b) Show that if V is translation invariant and $\psi(t, \mathbf{x}_1, \dots, \mathbf{x}_N)$ is a solution of the Schrödinger equation, then so is

$$\psi'(t', \mathbf{x}'_1, \dots, \mathbf{x}'_N) = \exp\left[\frac{i}{\hbar} \sum_{i=1}^N m_i (\mathbf{x}'_i \cdot \mathbf{v} - \frac{1}{2} \mathbf{v}^2 t')\right] \psi\left(t', \mathbf{x}'_1 - \mathbf{v}t', \dots, \mathbf{x}'_N - \mathbf{v}t'\right). \quad (7)$$

Problem 7: Polarization identity

Verify that

$$\langle \psi | \phi \rangle = \frac{1}{4} \left(\|\psi + \phi\|^2 - \|\psi - \phi\|^2 - i\|\psi + i\phi\|^2 + i\|\psi - i\phi\|^2 \right), \quad (8)$$

using the properties of an inner product. The polarization identity allows us to express inner products in terms of norms.