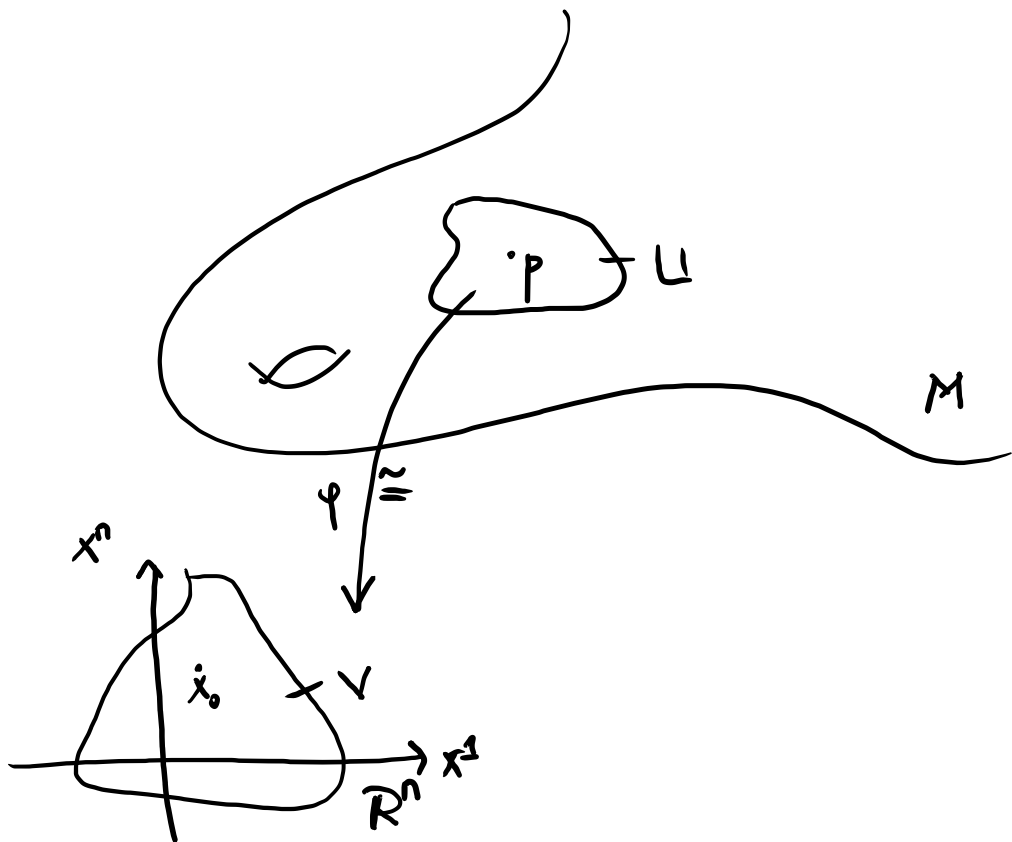


Lecture 07, 09.12.2022

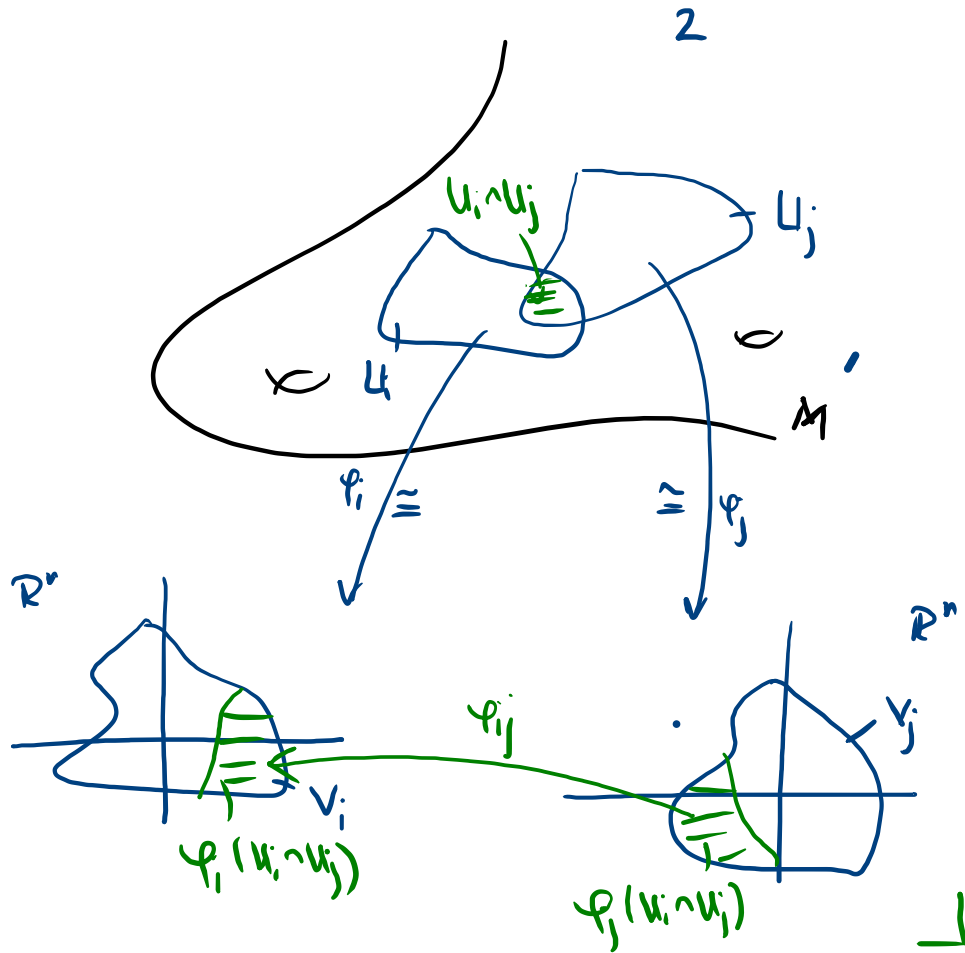
Remember:

• top. mfd. of
dimension $n \in \mathbb{N}$



• differentiable structure
on a top. mfd.

• $\varphi_{ij} = \varphi_i \circ \varphi_j^{-1}$
transition functions of
an atlas $\sigma = (\varphi_i)$
If all φ_{ij} are diff.,
 σ is called diff.
 $c = [\sigma]$ equiv. class



(9.5) Remarks. (a) On a given topological n -fold it could be that there are many different differentiable structures. (It is also possible, that there exists no one at all). Trivial example: Consider $\mathbb{R} = M$ which is a top. mfd. of dimension 1, of course. Now consider ^{the} following atlases consisting of a single chart:

$$\mathcal{O}_1 = (\varphi = \text{id} : \overset{M}{\mathbb{R}} \rightarrow \mathbb{R})$$

$$\mathcal{O}_2 = (\varphi = \text{pot}_3 : \mathbb{R} \rightarrow \mathbb{R}, x \mapsto x^3)$$

These are both differentiable since the only transition function of a single-chart-atlas is $\varphi \circ \varphi^{-1} = \text{id}$, which is, of course, differentiable. However, \mathcal{A} and \mathcal{B} are not equivalent, so $\mathcal{C}_1 = [\mathcal{A}]$ and $\mathcal{C}_2 = [\mathcal{B}]$ define different structures on $M = \mathbb{R}$. Indeed, the transition $\varphi \circ \psi^{-1}: \mathbb{R} \rightarrow \mathbb{R}$ of the atlas $\mathcal{A} + \mathcal{B} = (\varphi, \psi)$ of \mathbb{R} is not differentiable (in $x=0$), since

$$\varphi \circ \psi^{-1}(x) = \sqrt[3]{x}.$$

(However, we will see in a moment, that (\mathbb{R}, c_1) and (\mathbb{R}, c_2) are diffeomorphic, $(\mathbb{R}, c_1) \cong (\mathbb{R}, c_2)$. Namely via $\Phi: \mathbb{R} \rightarrow \mathbb{R}, p \mapsto \sqrt[3]{p}$.

(b) Among all differentiable atlases in a given differentiable structure, there exists a „maximal“ one, taking simply all charts of all these atlases (without repetition) together. Another possibility of defining a diff. str. would be therefore to define it as a „maximal differentiable atlas“. However, in general, a concrete diff. structure will be given usually in terms of a

rather poor atlas consisting of only a few charts.

(9.6) Examples. (a) \mathbb{R}^n has a standard structure $\sigma = (\varphi)$ given by $\varphi = \text{id}$.

(b) If M^n is a diff. mfd. given by a diff. atlas $\sigma = (\varphi_i)_{i \in I}$, any open subset $N \subseteq M$ inherits the structure of a diff. mfd. of the same dimension. Of course, N is a top. n -fold, and the induced diff. structure is simply given by the restrictions $(\varphi_i : U_i \cap N \rightarrow W_i)_{i \in I}$ (with $W_i := \varphi_i(U_i \cap N) \subseteq V_i \subseteq \mathbb{R}^n$) is independent of the

representative.

(c) In particular, every open subset $V \subseteq \mathbb{R}^n$ is a diff. mfd. of dim. n via the identity chart.

(d) Let V be a real vector space of dimension $n \in \mathbb{N}$.

Then choosing a basis (v_1, \dots, v_n) of V yields a coordinate isomorphism $\varphi: V \rightarrow \mathbb{R}^n$. We give V the topology via φ .

Then V becomes a top. mfd. of dimension n and φ will be a homeomorphism. Another basis would give

the same topology on V , since the change $\bar{\varphi} \circ \varphi: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a linear isomorphism of \mathbb{R}^n , so a homeo-

homeomorphism. We can give now V also a diff. structure via φ and, of course, also this is independent of the chosen basis, since $\tilde{P}^{-1} \circ \varphi$ is even a diffeomorphism. This gives the abstract vector space V in a natural way the structure of an n -dimensional diff. manifold.

(9.7) The n -sphere The most prominent example of a "true" manifold (meaning that you cannot find an atlas with a single chart) will be perhaps the following:

$$S^n = \{ p \in \mathbb{R}^{n+1} : \|p\|^2 = 1 \} \quad (n \in \mathbb{N}_0)$$

with its subspace topology of \mathbb{R}^{n+1} is hausdorff and of countable topology since \mathbb{R}^{n+1} is. It is connected and compact (by Heine-Borel). So it is not possible to cover S^n with a single chart (since an open non-empty $V \subseteq \mathbb{R}^n$ is not compact). Consider now for

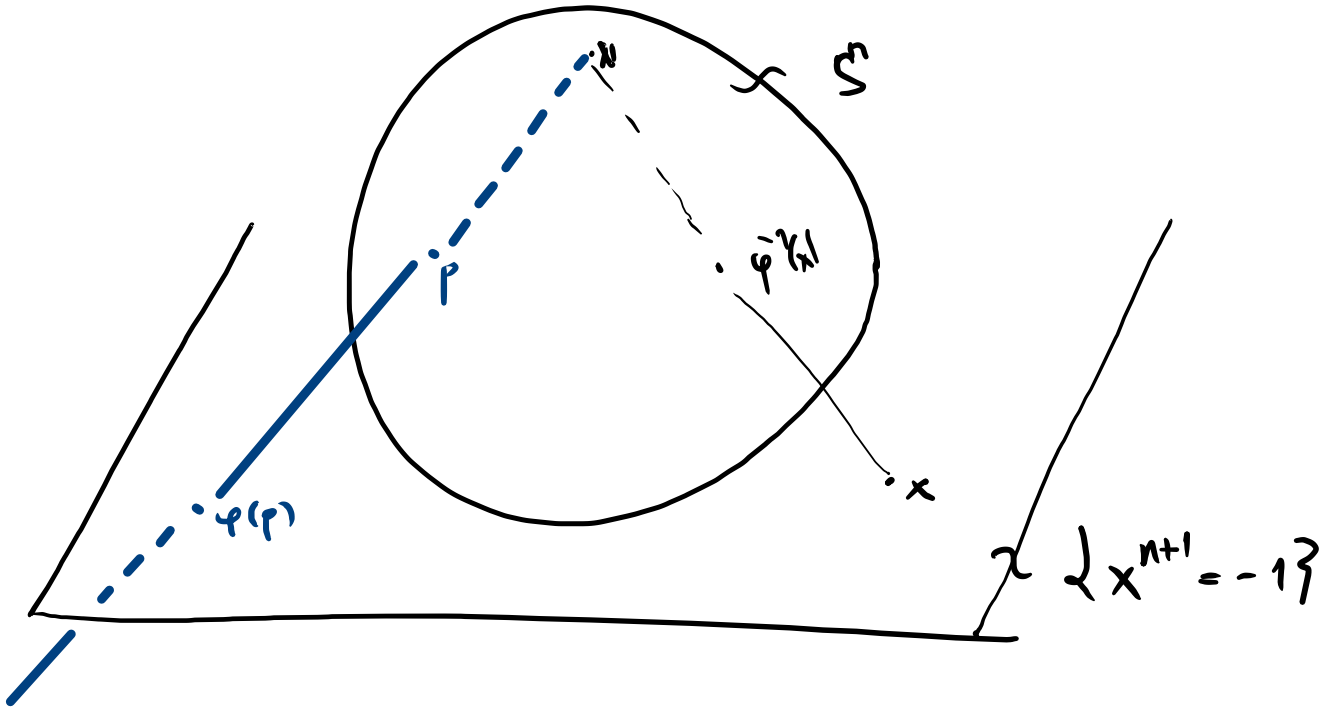
$$N = (0, \dots, 0, 1) \quad \text{and} \quad S = (0, \dots, 0, -1)$$

the so-called stereographic projections

$$\gamma: S^n \setminus \{N\} \rightarrow \mathbb{R}^n, p \mapsto \frac{1}{1-p^{n+1}} (p^1, \dots, p^n).$$

(For reasons that become clear later I denote the components of a vector $x \in \mathbb{R}^n$ by x^i ($i = 1, \dots, n$) with a superscript.)

\mathbb{R}^{n+1}



$$\{x^{n+1} = -1\}$$

resp.

$$\psi: S^n \setminus \{s\} \rightarrow \mathbb{R}^n, p \mapsto \frac{1}{1+p^{n+1}} (p^1, \dots, p^n)$$

Then φ and ψ are continuous (since restrictions of cont. maps from $\mathbb{R}^{n+1} \setminus \{x^{n+1} = 1\}$ to \mathbb{R}^n resp. $\mathbb{R}^{n+1} \setminus \{x^{n+1} = -1\}$ and bijective, since

$$x = (x^1, \dots, x^n) \mapsto \frac{1}{1+\|x\|^2} (2x^1, \dots, 2x^n, -1+\|x\|^2)$$

$$\mathbb{R}^n \longrightarrow S^n \setminus \{N\}$$

resp.

$$x = (x^1, \dots, x^n) \longmapsto \frac{1}{1 + \|x\|^2} (2x^1, \dots, 2x^n, 1 - \|x\|^2),$$

$$\mathbb{R}^n \longrightarrow S^n - \{s\},$$

are inverses for φ and ψ . These are obviously also cont.,
 so φ and ψ are homeomorphisms and, of course

$$S^n = (S^n - \{N\}) \cup (S^n - \{s\}).$$

Therefore S^n is a topological mfd. of dimension n .

Next observe that the atlas $\sigma = (\varphi, \psi)$ is differentiable since for the transitions $\varphi \circ \varphi^{-1}$ and $\varphi \circ \psi^{-1}$ from $\mathbb{R}^n - \{0\} \rightarrow \mathbb{R}^n - \{0\}$ we have (exercise)

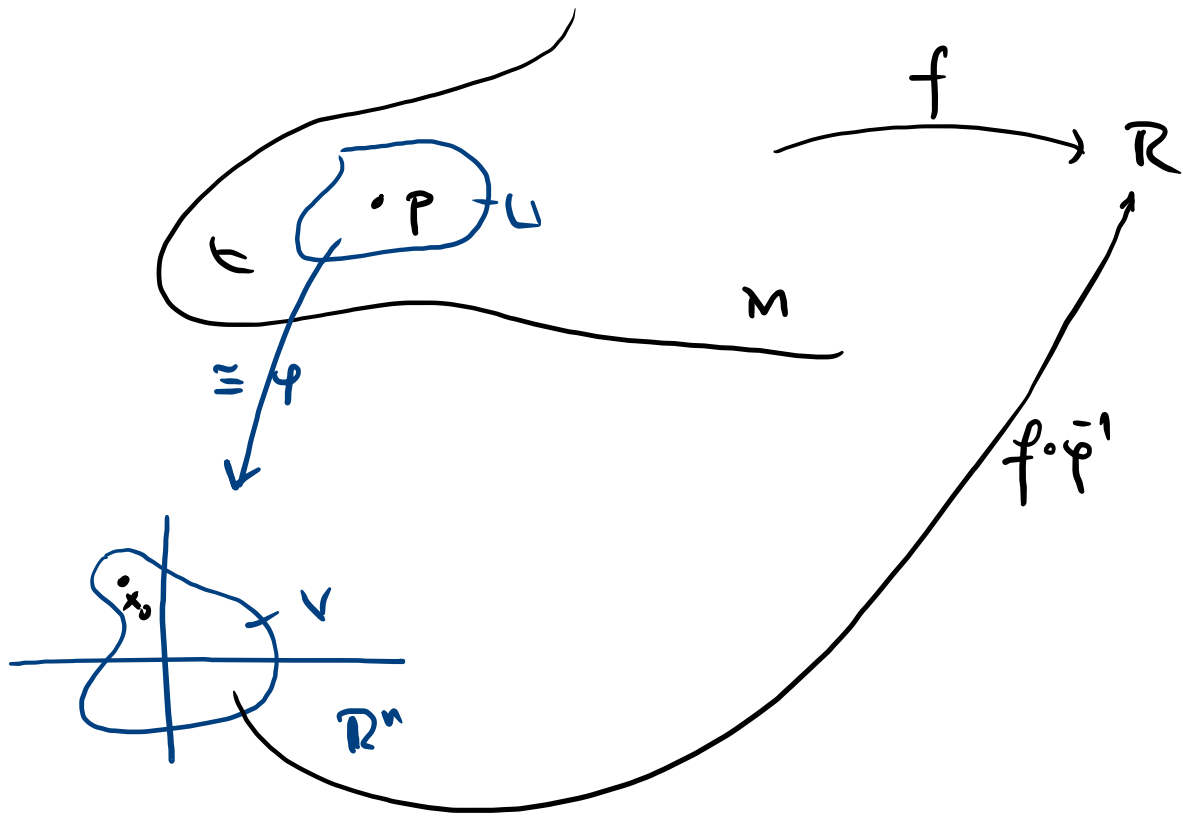
$$\varphi \circ \varphi^{-1}(x) = \varphi \circ \psi^{-1}(x) = \frac{x}{\|x\|^2}.$$

Thus $(S^n, [(\varphi, \psi)])$ is a diff. mfd. of dimension n .

(9.5) Definition. Let (M, c) be a differ. mfd. (written in the following simply by M) and $p \in M$. A continuous function $f: M \rightarrow \mathbb{R}$ is called differentiable at p , if for one (and then every) chart $\varphi: U \rightarrow V \subseteq \mathbb{R}^n$ (of some atlas $\sigma \in c$) around p (i.e. $p \in U$) the composition

$$f|_U \circ \varphi^{-1}: V \rightarrow \mathbb{R}$$

is differentiable in $x_0 = \varphi(p)$. f is called differen-
tiable if it is differentiable in all points $p \in M$.



(9.9) Remarks. As already motivated this definition is indeed independent of the chosen chart (and the chosen atlas \mathcal{A} of the structure c). Namely, if $\varphi: \tilde{U} \rightarrow \tilde{V} \subset \mathbb{R}^n$ is another chart, then

$$f|_{\tilde{U}} \circ \varphi^{-1} = (f|_U \circ \bar{\varphi}^{-1}) \circ (\varphi \circ \bar{\varphi}^{-1}) \quad \text{on } \varphi(U \cap \tilde{U})$$

and therefore also differentiable in $\varphi(p)$.

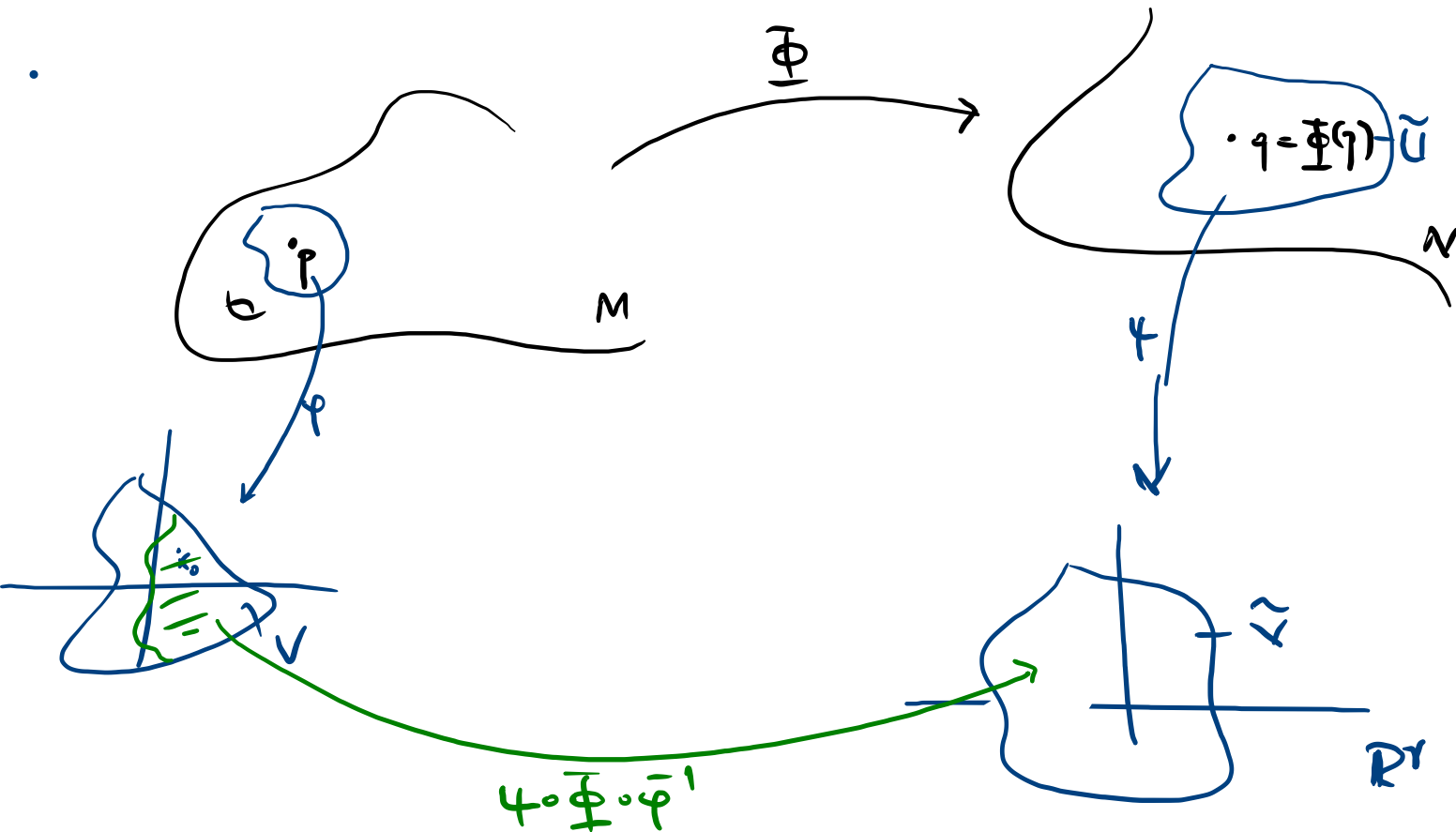
(9.10) Definition. Let M^n and N^r be diff. mfds.,

$p \in M$ and $\underline{\Phi} : M \rightarrow N$ a continuous map.

(a) Then $\underline{\Phi}$ is called differentiable in p , if for some (and then every) choice of charts $\varphi : U \rightarrow V \subseteq \mathbb{R}^n$ around p and $\psi : \tilde{U} \rightarrow \tilde{V} \subseteq \mathbb{R}^r$ around $q := \underline{\Phi}(p) \in N$ the composition

$$\psi \circ \underline{\Phi} \circ \varphi^{-1} : \varphi(U \cap \underline{\Phi}^{-1}(\tilde{U})) \rightarrow \tilde{V} \subseteq \mathbb{R}^r$$

is differentiable in $x_0 = \varphi(p)$.



(b) $\tilde{\Phi}$ is called diff., if Φ is diff. in all points $p \in M$.