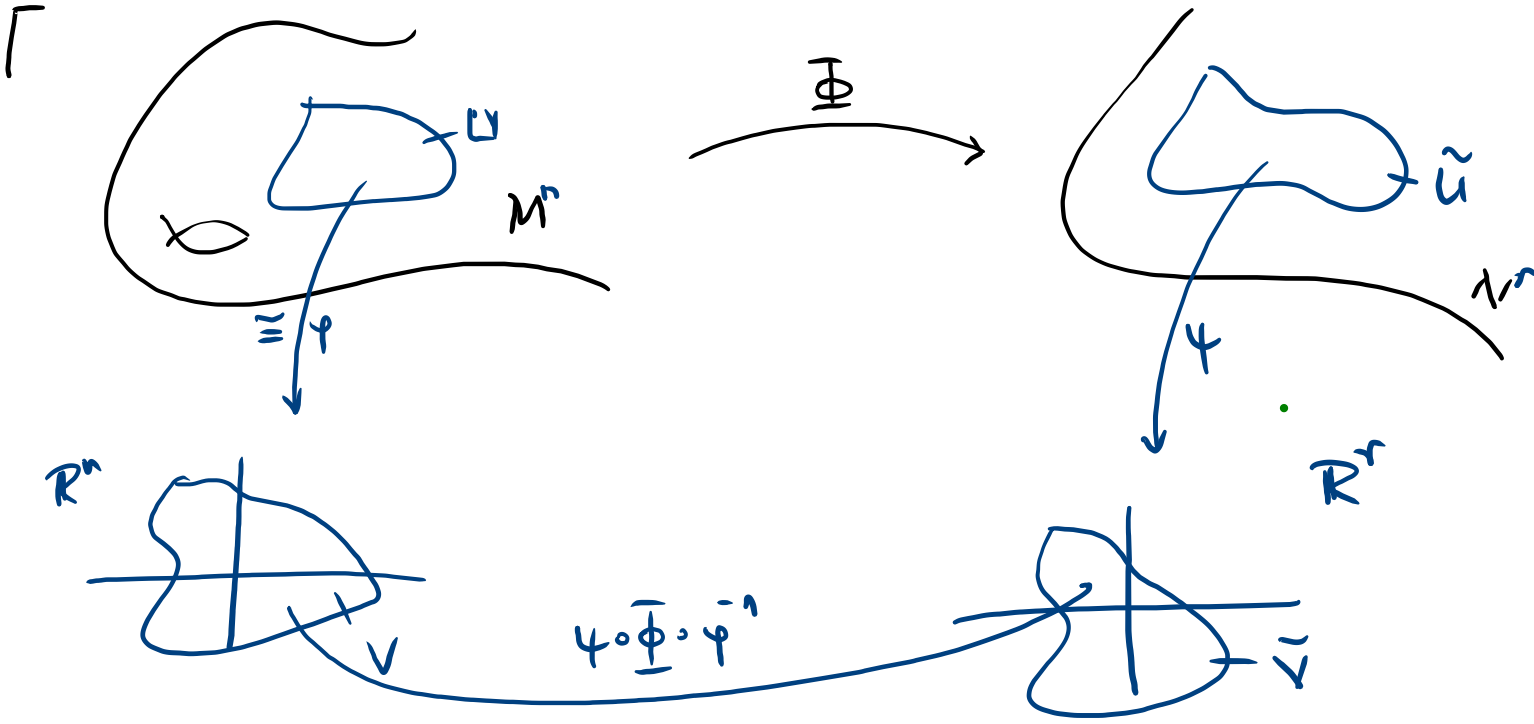


Lecture-08, 16.12.2022



$\bar{\Phi}$ differentiable $\Leftrightarrow \psi \circ \bar{\Phi} \circ \bar{\varphi}^{-1}$ is differentiable in the usual sense, for all charts φ of M and ψ of N

(9.10)

(c) If $\bar{\Phi}$ is differentiable and bijective so that also $\bar{\Phi}^{-1}: N \rightarrow M$ is differentiable, then $\bar{\Phi}$ is called a diffeomorphism, $M \cong N$. M and N are called diffeomorphic, if there exists a diffeomorphism.

(9.11) Examples. Let $M = \mathbb{R}$ and $c_1 = [(\varphi)]$, $c_2 =$

$= [(\varphi)]$ be the diff. structures on \mathbb{R} given by $\varphi = \text{id}_{\mathbb{R}}$ and $\psi = \text{pot}_3$. We know already that $c_1 \neq c_2$. However, observe that the continuous $\underline{\Phi}: (\mathbb{R}, c_1) \rightarrow (\mathbb{R}, c_2)$, given by

$$p \mapsto \sqrt[3]{p},$$

is a diffeomorphism, since in local coordinates we have that

$$\psi \circ \underline{\Phi} \circ \varphi^{-1}(x) = \psi \circ \underline{\Phi}(x) = \text{pot}_3(\sqrt[3]{x}) = x = \text{id}(x)$$

as well as $\varphi \circ \Phi^{-1} \circ \Psi^{-1} = \text{id}$, which are differentiable.

(9.12) Remarks. (a) If $f: M \rightarrow \mathbb{R}$ is a diff. function in the sense of Definition (9.8), then f is obviously a diff. map in the sense of Definition (9.10), if we give \mathbb{R} its standard structure [$\varphi = \text{id}$].

(b) By the way, it is possible that a top. mfd. M^n carries no diff. structure at all (only for $n \geq 4$) and, quite surprisingly, it is also possible that there exists pairwise non-diffeomorphic structure on certain top.

manifolds. (Not for $n \leq 3$.) A spectacular result of John Milnor was that on the S^7 there exist, besides the standard structure, exactly 27 other pairwise non-diffeomorphic (so called exotic) structures.

§ 10. The tangent bundle

(10.1) Motivation. Remember from Calculus: A sub-manifold of \mathbb{R}^{n+k} of dimension $n \in \mathbb{N}$ is a closed subset $M \subseteq \mathbb{R}^{n+k}$ so that for each $p \in M$ there exists

an open subd. $U \subseteq \mathbb{R}^{n+k}$ and a diff. map $F: U \rightarrow \mathbb{R}^k$
 so that:

$$(i) F^{-1}(0) = U \cap M$$

$$(ii) \text{rank}(DF_p: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k) = k$$

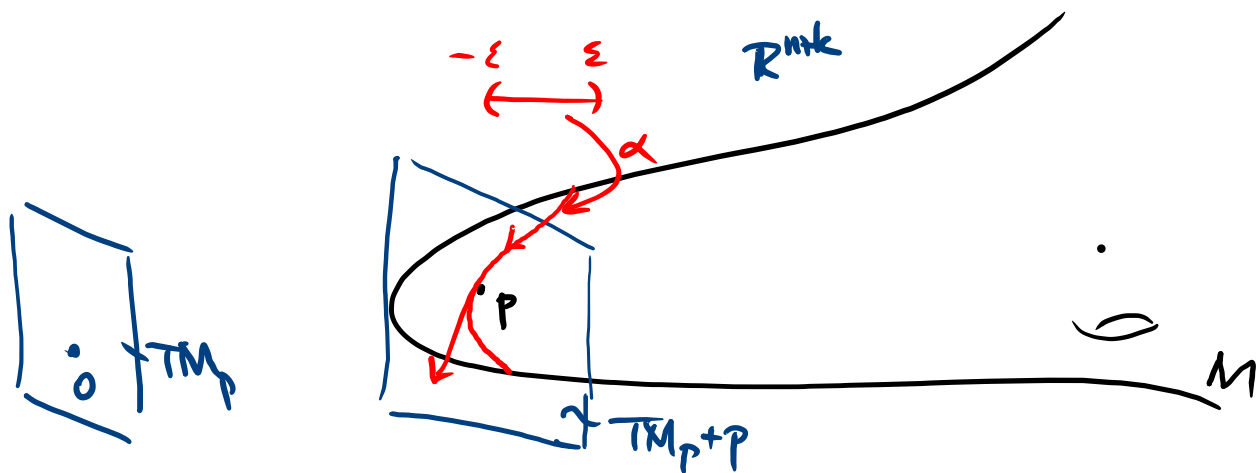
Then:

$$TM_p := \ker(DF_p) \subseteq \mathbb{R}^{n+k}$$

was called the tangent space of M in p and it was

$$TM_p = \{ \dot{\alpha}(0) \in \mathbb{R}^{n+k} : \exists \varepsilon > 0, \alpha : (-\varepsilon, \varepsilon) \rightarrow M \text{ diff.} \\ \text{with } \alpha(0) = p \}$$

the space of tangent vectors of curves through p lying on M.



(6) Problem. How can one define " TM_p " of an abstract manifold M^n (as a vector space of dimension n)?

Idea. Interpret any tangent vector $\xi = \dot{\alpha}(0) \in TM_p \in \mathbb{R}^{n \times k}$ as a directional derivative on differentiable functions $f: W \rightarrow \mathbb{R}$, defined on an open nhd. $W \subseteq M$ of $p \in M$.

$$\xi(f) := \left. \frac{d}{dt} \right|_{t=0} (f \circ \alpha)(t)$$

Observe: ξ is an \mathbb{R} -linear derivation, i.e.:

$$\xi(f \cdot g) = \xi(f) \cdot g(p) + f(p) \cdot \xi(g)$$

since with the Leibniz rule

$$\begin{aligned} \frac{d}{dt} (f \cdot g \circ \alpha)(t) &= \frac{d}{dt} (f \circ \alpha \cdot g \circ \alpha)(t) = (f \circ \alpha)'(0) \cdot g \circ \alpha(0) \\ &\quad + f \circ \alpha(0) \cdot (g \circ \alpha)'(0) \\ &= \xi(f) \cdot g(p) + f(p) \cdot \xi(g). \end{aligned}$$

(10.2) Definition: Let M^n be a top. mfd. of dim. n

A topological atlas $\mathcal{A} = (\varphi_i : U_i \rightarrow V_i)$ is called a C^∞ -atlas if all transition functions φ_{ij} are C^∞ -maps. Two atlases \mathcal{A} and \mathcal{B} are called equivalent, if $\mathcal{A} + \mathcal{B}$ is a C^∞ -atlas as well. An equivalence class $c = [\mathcal{A}]$ of C^∞ -atlases is called a C^∞ -structure on M . A C^∞ -manifold, or smooth manifold, of dimension $n \in \mathbb{N}$ is a pair (M, c) .

(10.3) Remark. (a) In an obvious way we define smooth functions $f : M \rightarrow \mathbb{R}$ and smooth maps $\underline{F} : M \rightarrow N$ between smooth mfd's. M and N .

(b) For every open subset $U \subseteq M$, M a smooth mfd., we denote

$$\Sigma_M(U) := \{f: U \rightarrow \mathbb{R} : f \text{ is smooth}\} \quad (\text{or } C^\infty(U)).$$

Then $\Sigma(U)$ has the structure of an \mathbb{R} -algebra via

$$(f+g)(p) := f(p) + g(p)$$

$$(\lambda \cdot f)(p) := \lambda \cdot f(p)$$

$$(f \cdot g)(p) := f(p) \cdot g(p)$$

for $f, g \in \mathcal{E}(U)$, $\lambda \in \mathbb{R}$. $\Gamma \mathcal{E}_M$ becomes a sheaf over M .

(10.4) Definition. Let M be a smooth mfd. and $p \in M$.
On the set theoretic sum

$$\sum_{U \in \mathcal{U}(p) \text{ open}} \mathcal{E}(U)$$

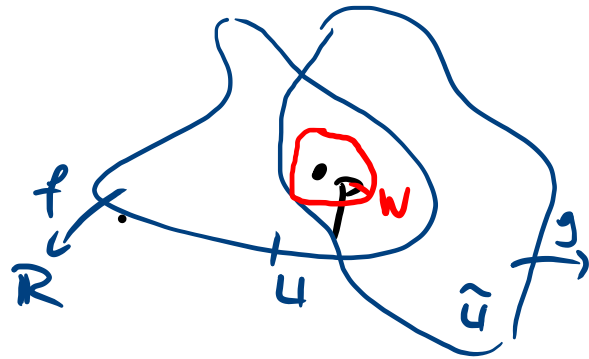
(where $\mathcal{U}(p)$ denotes the set of all mfd's of p).
we define the following equivalence relation:

$f \in \mathcal{E}(U)$ and $g \in \mathcal{E}(\tilde{U})$ ($U, \tilde{U} \in \mathcal{V}(p)$ open) are called equivalent, $f \sim g$, if there exists an open $W \in \mathcal{V}(p)$ with $W \subseteq U \cap \tilde{U}$ such that $f|_W = g|_W$.

The quotient set

$$\mathcal{E}_p(M) := \left(\sum_U \mathcal{E}(U) \right) / \sim$$

is called the space of smooth function germs in p .



(10.5) Remarks. (a) $\mathcal{E}_p(M)$ inherits from all $\mathcal{E}(u)$ ($u \in \mathcal{U}(A)$ open), the structure of an \mathbb{R} -algebra since we can define addition, scalar multiplication and inner multiplication via representatives: if we write $s = f_p := [f] \in \mathcal{E}_p(M)$, $t = g_p \in \mathcal{E}_p(M)$, $\lambda \in \mathbb{R}$, then

$$s + t := f_p + g_p := (f + g)_p$$

$$\lambda \cdot s := \lambda \cdot f_p := (\lambda f)_p$$

$$s \cdot t := f_p \cdot g_p := (fg)_p$$

This is well defined and makes $\mathcal{E}_p(M)$ into a

(local) algebra.

(6) The \mathbb{R} -algebra $A = \mathcal{E}_p(M)$ comes along with a so called evaluation homomorphism $\varrho: A \rightarrow \mathbb{R}$, namely

$$\varrho(f_p) := f(p) =: f_p(p),$$

which is obviously well defined. Observe, that you cannot evaluate a germ $\zeta \in \mathcal{E}_p(M)$ in another point $q \in M$ different from p .

(10.6) Definition. Let M^n be a smooth mfd. and $p \in M$. Let $\mathcal{E}_p(M)$ the \mathbb{R} -algebra of smooth germs of M in p .

(a) A tangent vector of M in p is a derivation on $\mathcal{E}_p(M)$, i.e., a linear map $\xi: \mathcal{E}_p(M) \rightarrow \mathbb{R}$ satisfying

$$\xi(f_p \cdot g_p) = \xi(f_p) \cdot g_p(p) + f_p(p) \cdot \xi(g_p).$$

(b) The tangent space of M in p is the \mathbb{R} -vector space

$$TM_p := \text{Der}_{\mathbb{R}}(\mathcal{E}_p(M), \mathbb{R}).$$

(It has in a natural way the structure of an \mathbb{R} -vector space as a subspace of $\text{Hom}_{\mathbb{R}}(\xi_p(M), \mathbb{R})$.)

(10.7) Example. Let $\varepsilon > 0$ and $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ a smooth curve on M through p . We define $\xi: \xi_p(M) \rightarrow \mathbb{R}$ by

$$\xi(f_p) := \left. \frac{d}{dt} \right|_{t=0} (f \circ \alpha)(t)$$

and check immediately that this is well defined, it is obviously linear and indeed a derivation (cf. (10.1)). We

will write

$$\dot{\alpha}(0) := \xi \in TM_p$$

for this derivation and call it the tangent vector of the curve α in p .

(10.8) Example. Let M^n be a smooth mfd., $p \in M$, and $\varphi: U \rightarrow V \subseteq \mathbb{R}^n$ a chart around p , and $x_0 = \varphi(p) \in V$.
For every $j = 1, \dots, n$ we define

$$\frac{\partial}{\partial x^j} \Big|_p : \mathcal{E}_p(M) \rightarrow \mathbb{R}, f_p \mapsto \frac{\partial}{\partial x^j} \Big|_{x_0} (f \circ \bar{\varphi}^{-1})$$

(10.9) Remarks. (a) Then $\frac{\partial}{\partial x^j} \Big|_p$ is well defined, it is obviously linear (since $(f+g) \circ \bar{\varphi}^{-1} = f \circ \bar{\varphi}^{-1} + g \circ \bar{\varphi}^{-1}$ and $(\lambda f) \circ \bar{\varphi}^{-1} = \lambda \cdot (f \circ \bar{\varphi}^{-1})$) and it is also a derivation, since with the Leibniz rule we have:

$$\begin{aligned} \frac{\partial}{\partial x^j} \Big|_p (f_p \cdot g_p) &= \frac{\partial}{\partial x^j} \Big|_{x_0} (f \cdot g \circ \bar{\varphi}^{-1}) = \frac{\partial}{\partial x^j} \Big|_{x_0} (f \circ \bar{\varphi}^{-1} \cdot g \circ \bar{\varphi}^{-1}) \\ &= \frac{\partial}{\partial x^j} \Big|_{x_0} (f \circ \bar{\varphi}^{-1}) \cdot (g \circ \bar{\varphi}^{-1})(x_0) + (f \circ \bar{\varphi}^{-1})(x_0) \cdot \frac{\partial}{\partial x^j} \Big|_{x_0} (g \circ \bar{\varphi}^{-1})(x) \end{aligned}$$

$$= \frac{\partial}{\partial x^i} \Big|_p (f_1) \cdot g_1(p) + f_1(p) \cdot \frac{\partial}{\partial x^j} \Big|_p (g_1).$$

We call $\frac{\partial}{\partial x^j} \Big|_p \in T M_p$ the j coordinate vector w.r.t. the chart φ .

(b) Observe: If $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ is the curve

$$\alpha(t) = \varphi^{-1}(x_0 + t \cdot e_j)$$

(for $\varepsilon > 0$ small enough), then: $\dot{\alpha}(0) = \frac{\partial}{\partial x^j} \Big|_p$.

